

# Introduction to GEANT4

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# Tips and docs

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## User's guide

<https://geant4-userdoc.web.cern.ch/geant4-userdoc/UsersGuides/ForApplicationDeveloper/html/>

## Source code:

<https://www.apc.univ-paris7.fr/~franco/g4doxy/html/index.html>

# Course structure

- ▶ Marks based on the reproduction of results from some chosen publications
- ▶ Along the course you will have to approximate the acceptance of the experiment described in the paper:  
  
*Evaluation of proton inelastic reaction models in Geant4 for prompt gamma production during proton radiotherapy,*  
J. Jeyasugiththan and S. Peterson, 2015,  
Phys. Med. Biol. 60, 7617-7635
- ▶ The exercises will come in several level of difficulty, for you to choose

# Monte-Carlo simulation

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- ▶ In order to cross-check those results through a simulation, you will need to :
  - Define the geometry of the setup
  - Specify the beam configuration
  - Simulate real-world physics
  - Retrieve the generated data

# Monte-Carlo simulation

- ▶ Let's say you are running an experiment, and obtain some unexpected results.
  
- ▶ In order to cross-check those results through a simulation, you will need to :
  - Define the geometry of the setup
  - Specify the beam configuration
  - Simulate real-world physics → Randomness : Monte-Carlo
  - Retrieve the generated data

# Time to play

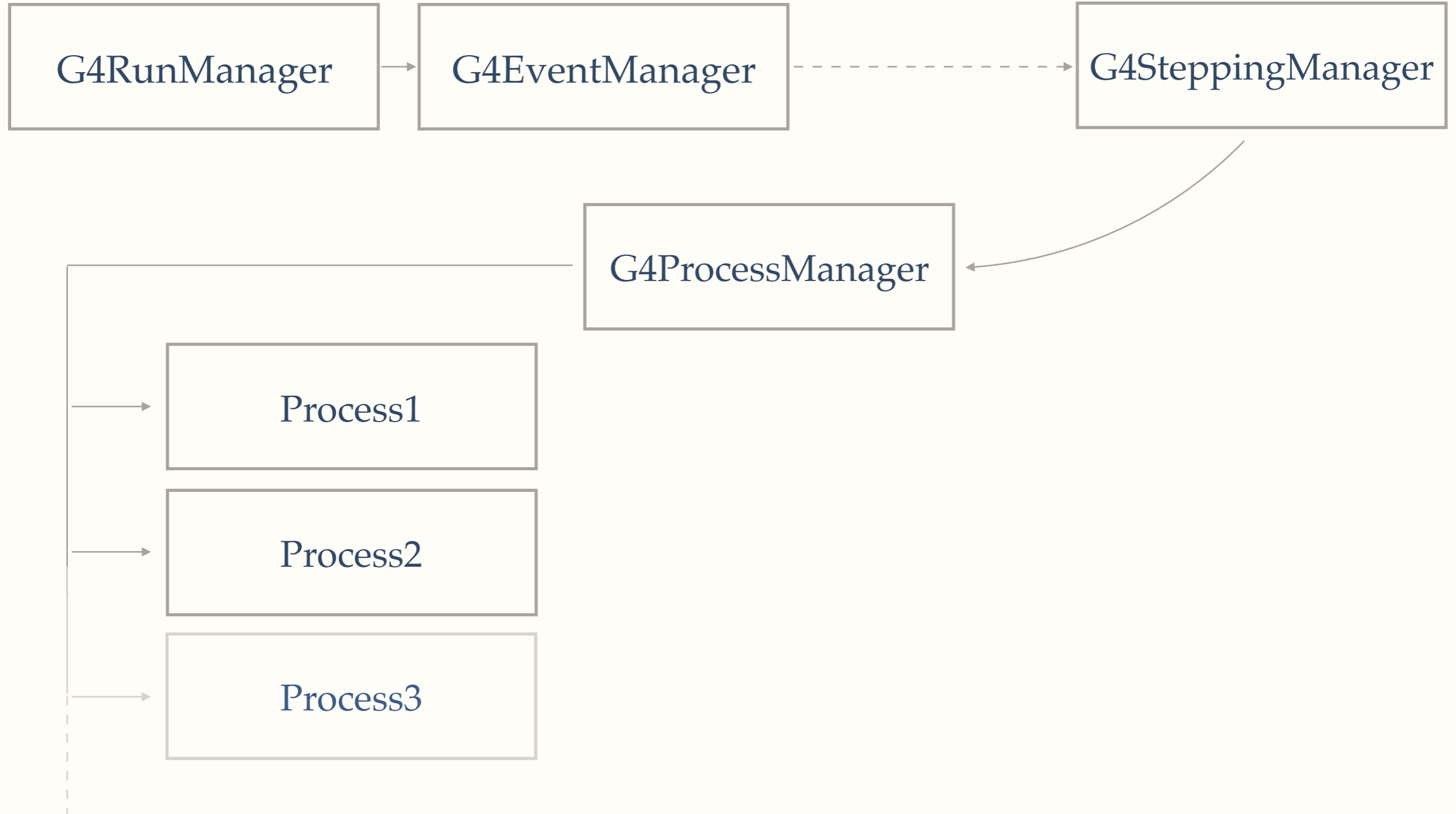
- ▶ Retrieve `example_source.tar.gz` from `/scratch/asecher/Geant4`
- ▶ Do not forget to setup your Geant4 and Root work environment  
`cernlib-use geant4 && cernlib-use root`
- ▶ Untar the file, and compile the sources inside an `example_build` directory you have created:

```
tar -xvf example_source.tar.gz
mkdir example_build && cd example_build
cmake ../example_source && make
```
- ▶ Run it, play with the interface, look at the source code and try to figure out what is happening

```
//with visualisation
./example
//inside the qt shell
/run/beamOn 10
```

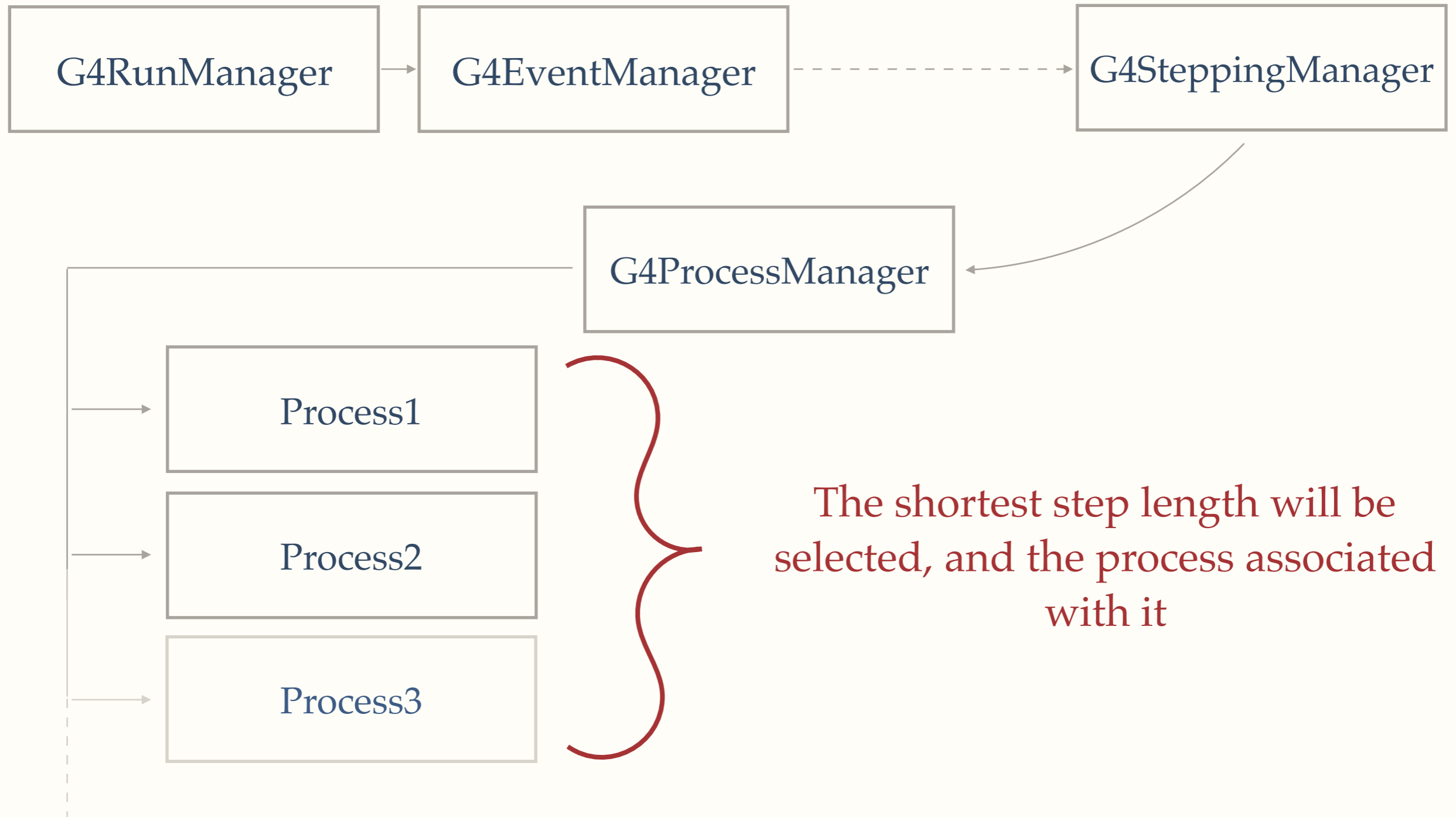
```
//without visualisation
./example run.mac
```

# Run structure





# Run structure



# Geometry

---

# Point of entry: main()

```
runManager->SetUserInitialization( new DetectorConstruction );
```

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```
runManager->SetUserInitialization( new DetectorConstruction );
```

```
void G4RunManager::SetUserInitialization  
    ( G4VUserDetectorConstruction* userInit )  
{  
    userDetector = userInit;  
}
```

Base class

Register the geometry inside the run manager

# Point of entry: main()

```
runManager->SetUserInitialization( new DetectorConstruction );
```

```
void G4RunManager::SetUserInitialization
    ( G4VUserDetectorConstruction* userInit )
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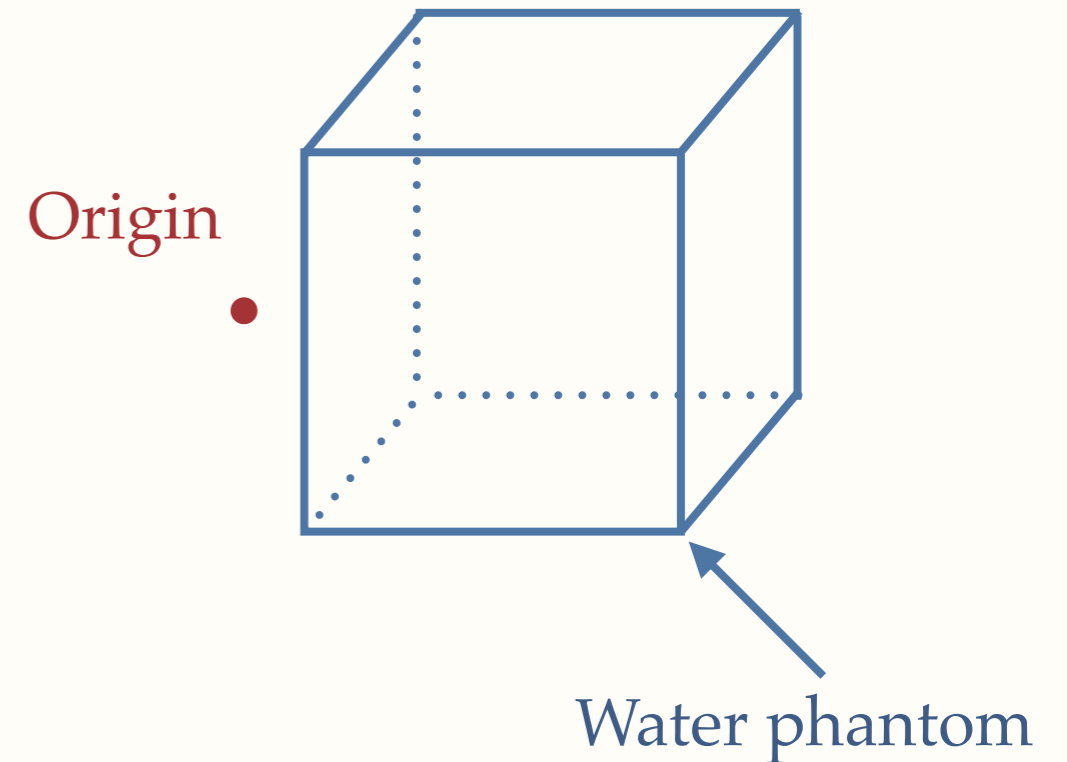
Register the geometry inside the run manager

```
void G4RunManager::InitializeGeometry()
{
    if (!userDetector) {
        ... //throws exception
    }
    ...
    kernel->DefineWorldVolume (userDetector->Construct(), false);
    ...
}
```

Check the existence of a user-defined geometry

# A bit of theory

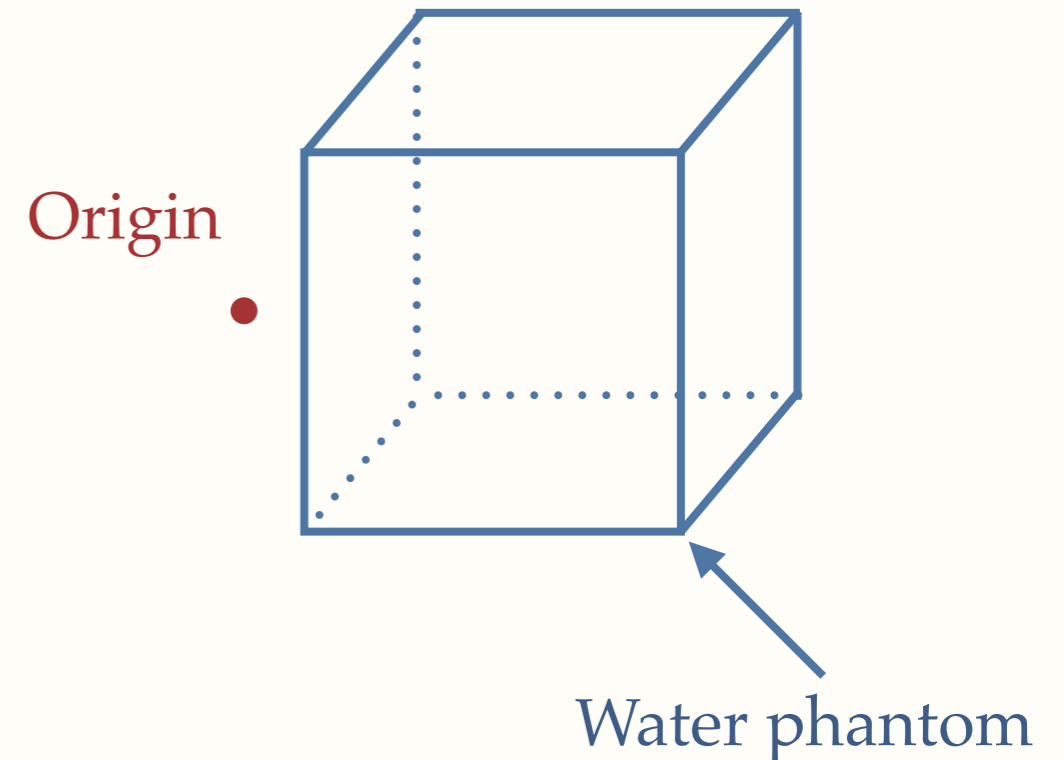
- ▶ What information do you need in order to define a volume ?



# A bit of theory

▶ What information do you need in order to define a volume ?

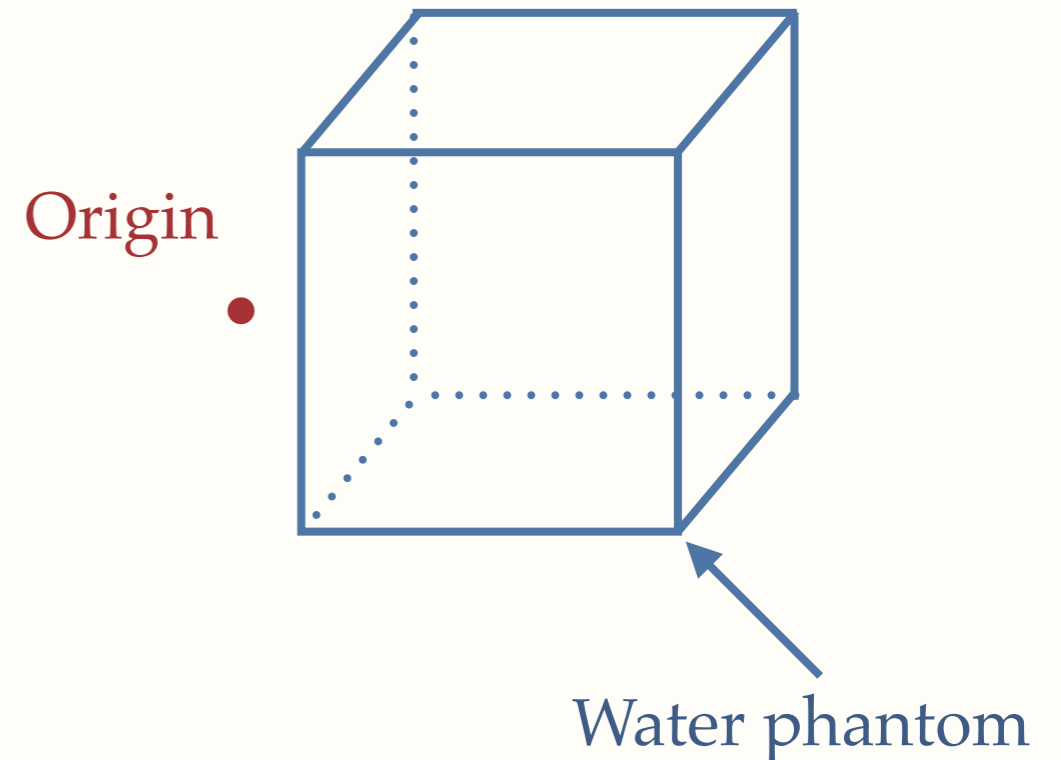
- form
- dimensions
- material
- position
- sensibility
- ...



# A bit of theory

- ▶ What information do you need in order to define a volume ?

- form
- dimensions
- material
- position
- sensibility
- ...

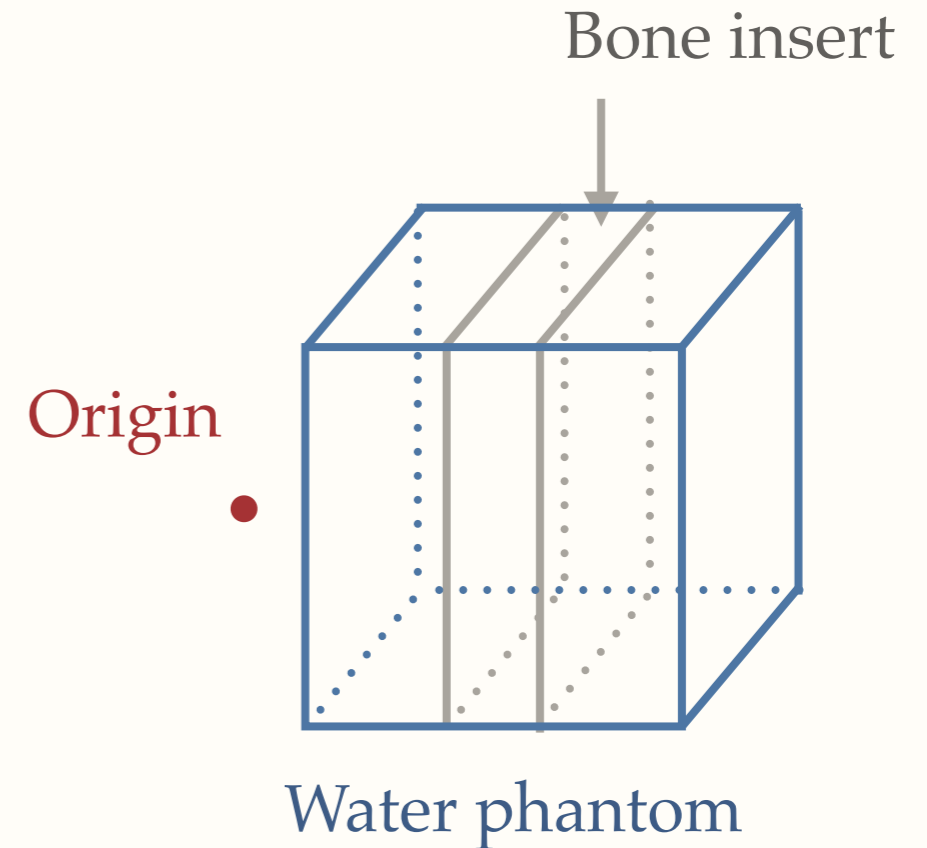


- ▶ The geometry definition is organised through **two layers**: logical and physical



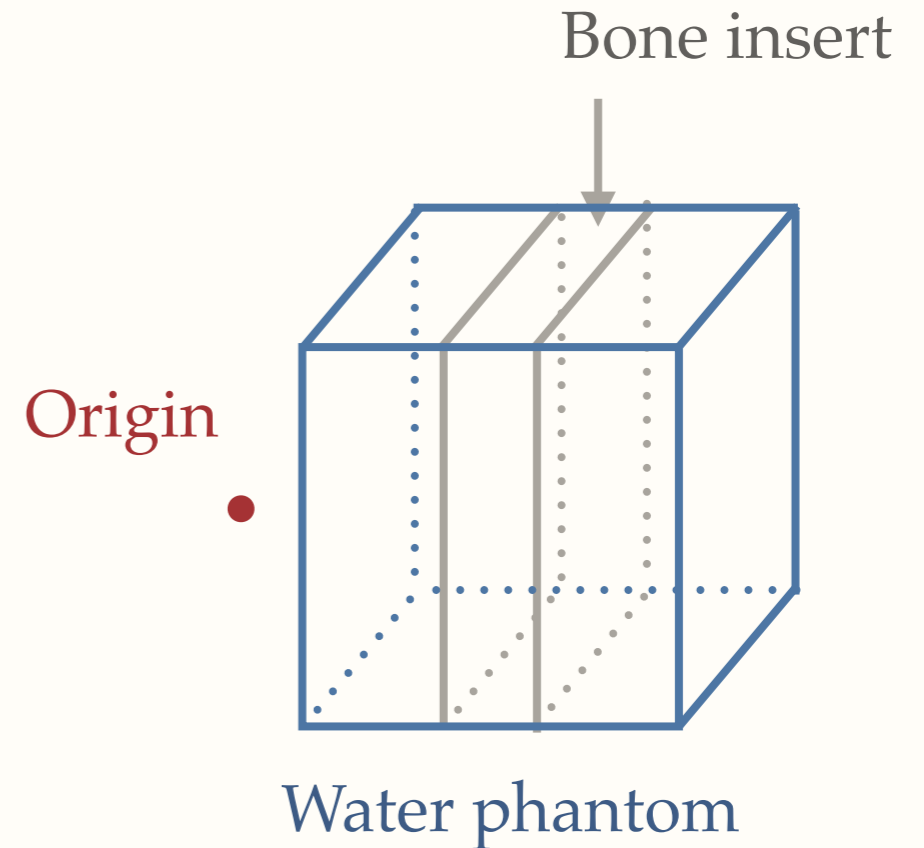
# A bit of theory

- ▶ How would you handle **overlapping volumes**?



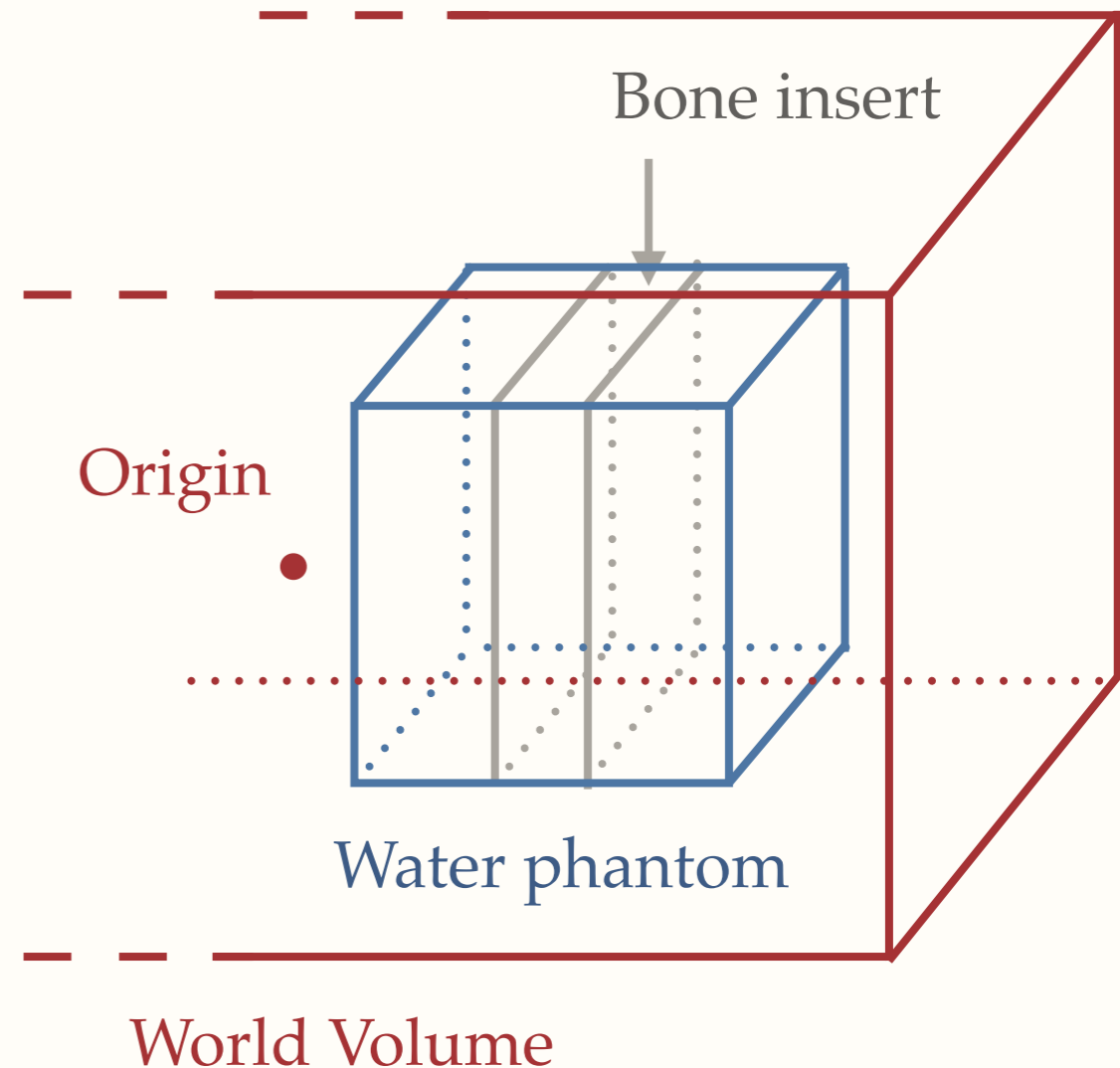
## A bit of theory

- ▶ How would you handle **overlapping volumes**?
- ▶ GEANT4 geometry is based around a **hierarchical structure**



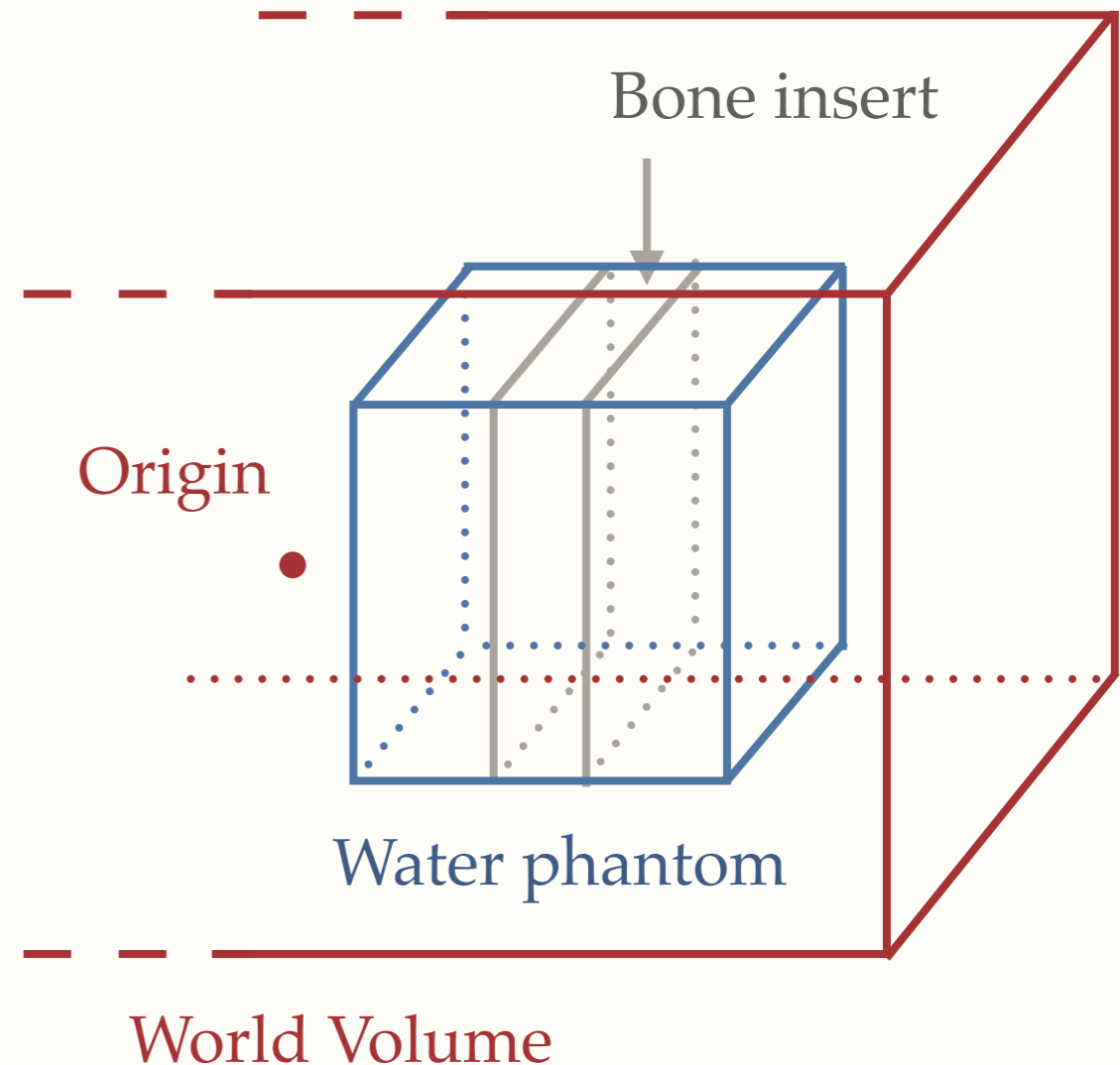
# A bit of theory

- ▶ How would you handle **overlapping volumes**?
- ▶ GEANT4 geometry is based around a **hierarchical structure**
- ▶ The frame of reference for the experiment needs to be defined: **world volume**



# A bit of theory

- ▶ How would you handle **overlapping** volumes?
- ▶ GEANT4 geometry is based around a **hierarchical structure**
- ▶ The frame of reference for the experiment needs to be defined: **world volume**
- ▶ Both the position inside of the hierarchy and in the world are defined in the physical volume layer



# Two different layers: logical volume

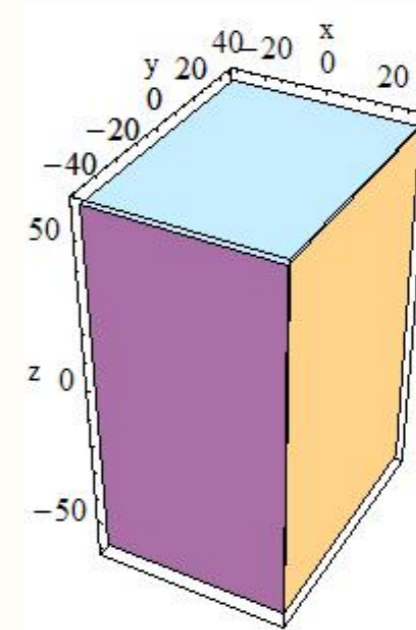
Defines form and dimensions

```
G4LogicalVolume ( G4VSolid* pSolid,  
                  G4Material* pMaterial,  
                  const G4String& name,  
                  G4FieldManager* pFieldMgr=0,  
                  G4VSensitiveDetector* pSDetector=0,  
                  G4UserLimits* pULimits=0,  
                  G4bool optimise=true );
```

Defines material contained inside of the volume

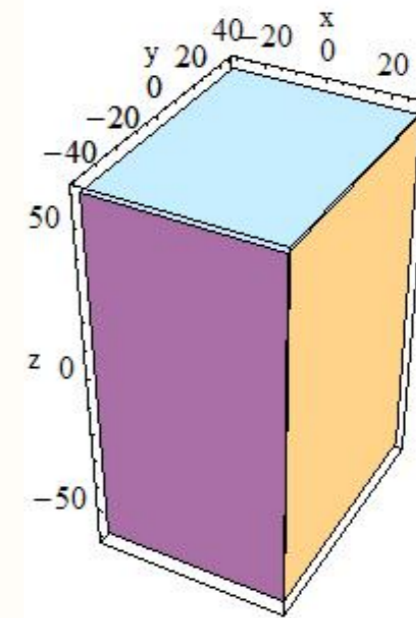
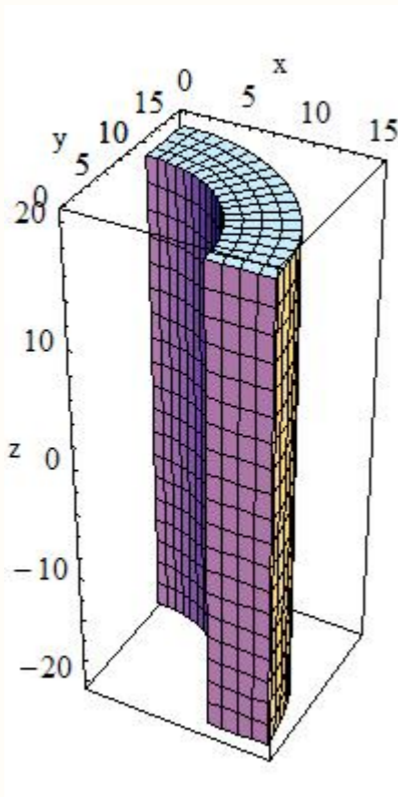
# How to define a form: CSG

```
G4Box ( const G4String& pName,  
         G4double pX,  
         G4double pY,  
         G4double pZ );
```



# How to define a form: CSG

```
G4Box ( const G4String& pName,
         G4double pX,
         G4double pY,
         G4double pZ );
```



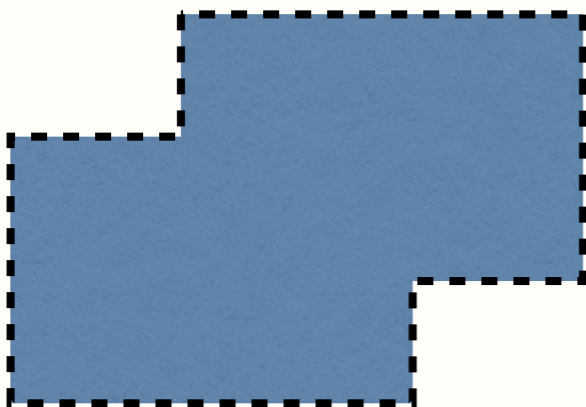
```
G4Tubs ( const G4String& pName,
          G4double pRMin,
          G4double pRMax,
          G4double pDz,
          G4double pSPhi,
          G4double pDPhi );
```

# How to define a form

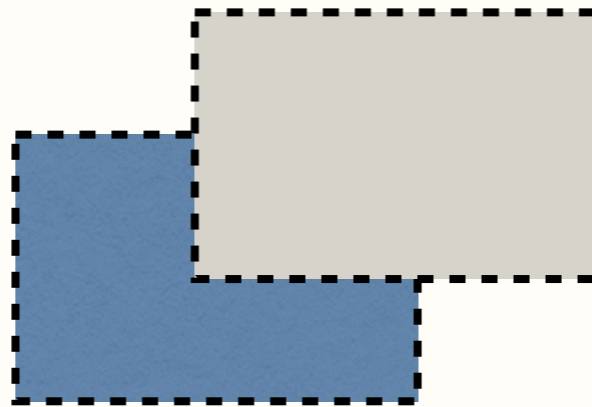
- ▶ Those volumes can be **combined** to form more complicated shapes

```
G4BooleanSolid( const G4String& pName,  
                G4VSolid* pSolidA ,  
                G4VSolid* pSolidB,  
                G4RotationMatrix* rotMatrix,  
                const G4ThreeVector& transVector );
```

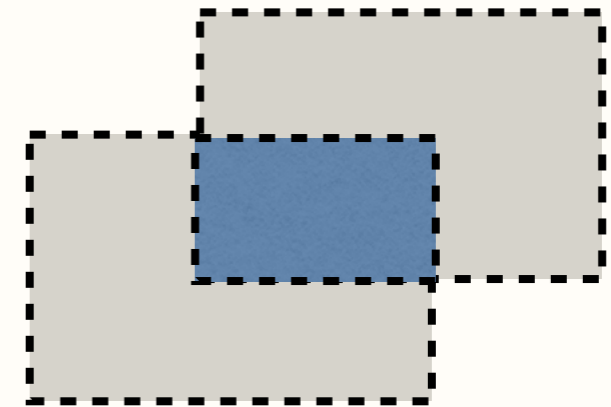
**G4UnionSolid**



**G4SubtractionSolid**



**G4IntersectionSolid**





# How to define a material

- ▶ What do you need to specify in order to define a material ?

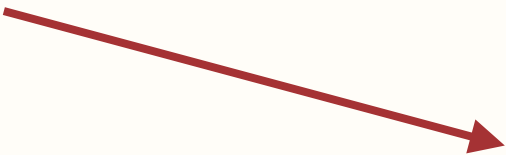
# How to define a material

- ▶ What do you need to specify in order to define a material ?
  - atoms
  - density
  - temperature
  - state
  - pressure
  - ...

# How to define a material

▶ What do you need to specify in order to define a material ?

- atoms
- density
- temperature
- state
- pressure
- ...



```
G4Element ( const G4String& name,  
             const G4String& symbol,  
             G4double   Zeff,  
             G4double   Aeff );
```

# How to define a material

```

G4Material ( const G4String& name,
              G4double   density,
              G4int      nComponents,
              G4State    state      = kStateUndefined,
              G4double   temp       = NTP_Temperature,
              G4double   pressure  = CLHEP::STP_Pressure );

```

Number of different elements



```


void G4Material::AddElement ( G4Element* element,
                              G4int      nAtoms   );
void G4Material::AddElement ( G4Element* element,
                              G4double   fraction );

```

Fraction of the total mass



Number of atoms of this  
element in the molecule/  
compound



# An example: logical volume

```
double phantom_size = 25 * CLHEP::cm;
G4VSolid* solidPhantom = new G4Box( "Phantom",
                                     0.5 * phantom_size,
                                     0.5 * phantom_size,
                                     0.5 * phantom_size );

auto* H = new G4Element("Hydrogen", "H", 1, 1.008 * CLHEP::g/
CLHEP::mole);
auto* O = new G4Element("Oxygen", "O", 8, 16.00 * CLHEP::g/
CLHEP::mole);
auto* H2O = new G4Material("Water", 1.0 * CLHEP::g/CLHEP::cm3, 2);
H2O->AddElement(H, 2);
H2O->AddElement(O, 1);

auto* logicPhantom = new G4LogicalVolume( solidPhantom,
                                           H2O,
                                           "Phantom" );
```

# Two different layers: physical volume

Defines rotation and translation with respect to mother volume

```
G4PVPlacement ( G4RotationMatrix *pRot,
  const G4ThreeVector &tlate,
  G4LogicalVolume *pCurrentLogical,
  const G4String& pName,
  G4LogicalVolume *pMotherLogical,
  G4bool pMany,
  G4int pCopyNo,
  G4bool pSurfChk=false );
```

The associated  
logical volume

The mother's logical volume

Logical volumes can be repeated several times,  
but the copy number need to be incremented  
each time

# An example: physical volume

```
auto * rotation = new G4RotationMatrix;
rotation->rotateY(45*CLHEP::deg);

new G4PVPlacement( rotation,
                  G4ThreeVector(0., 0., 10 * CLHEP::cm),
                  logicPhantom,
                  "Phantom",
                  logicWorld,
                  false,
                  0,
                  false);
```

# Point of use: G4RunManager

```
void G4RunManager::InitializeGeometry()
{
    if (!userDetector) {
        ... //throws exception
    }
    ...
    kernel->DefineWorldVolume (userDetector->Construct (), false);
    ...
}
```




# Point of use: G4RunManager

```
void G4RunManager::InitializeGeometry()  
{  
    if (!userDetector) {  
        ... //throws exception  
    }  
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```

# Point of use: G4RunManager

```
void G4RunManager::InitializeGeometry()
{
    if (!userDetector) {
        ... //throws exception
    }
    ...
    kernel->DefineWorldVolume (userDetector->Construct(), false);
    ...
}

void DefineWorldVolume ( G4VPhysicalVolume * worldVol,
                        G4bool topologyIsChanged = true );
```



# Point of use: G4RunManager

```
void G4RunManager::InitializeGeometry()
{
    if (!userDetector) {
        ... //throws exception
    }
    ...
    kernel->DefineWorldVolume (userDetector->Construct (), false);
    ...
}
```

```
void DefineWorldVolume ( G4VPhysicalVolume * worldVol,
                        G4bool topologyIsChanged = true );
```

```
virtual G4VPhysicalVolume*
    G4VUserDetectorConstruction::Construct () = 0;
```

The Construct() method must be overridden and must return the physical volume corresponding to the world volume

# Advices and warnings

- ▶ The world volume is the one defining the global coordinates of the simulation
- ▶ The volumes are positioned through their centre
- ▶ Specifying the units you are using is **always** a good idea
- ▶ In order to define basic materials, it is a good idea to look into the NIST Database (and to use the G4NistManager)  
[http://www.apc.univ-paris7.fr/~Efranco/g4doxy/html/G4NistMaterialBuilder\\_8cc-source.html](http://www.apc.univ-paris7.fr/~Efranco/g4doxy/html/G4NistMaterialBuilder_8cc-source.html)

# Exercise

- ▶ Goal : reproduction of the geometry given in the Jeyasugiththan publication
- ▶ Three difficulty levels:
  - (A) Fill-in the blanks
  - (B) Structural code
  - (C) Empty class
- ▶ Retrieve the chosen files in:  
`/scratch/asecher/Geant4/geometry_exercise`
- ▶ And the rest of the files needed to run the simulation in:  
`/scratch/asecher/Geant4/core_exercise`

Beam

---

# Point of entry: main()

```
runManager->SetUserAction(new PrimaryGeneratorAction);
```

# Point of entry: main()

```
runManager->SetUserAction(new PrimaryGeneratorAction);
```

```
void G4RunManager::SetUserAction(G4VUserPrimaryGeneratorAction*  
userAction)  
{  
    userPrimaryGeneratorAction = userAction;  
}
```

Base class

Registers the primary generator



# Point of entry: main()

```
runManager->SetUserAction(new PrimaryGeneratorAction);
```

```
void G4RunManager::SetUserAction(G4VUserPrimaryGeneratorAction*
userAction)
{
    userPrimaryGeneratorAction = userAction;
}
```

Base class

Registers the primary generator

```
G4Event* G4RunManager::GenerateEvent(G4int i_event)
{
    if(!userPrimaryGeneratorAction)
    {
        ...//throws exception
    }
    G4Event* anEvent = new G4Event(i_event);
    userPrimaryGeneratorAction->GeneratePrimaries(anEvent);
    ...
}
```

Checks the existence of a user primary generator

# Point of use: G4RunManager

```
G4Event* G4RunManager::GenerateEvent(G4int i_event)
{
    if (!userPrimaryGeneratorAction)
    {
        ...//throws exception
    }
    G4Event* anEvent = new G4Event(i_event);
    userPrimaryGeneratorAction->GeneratePrimaries(anEvent);
    ...
}
```



```
virtual void G4VUserPrimaryGeneratorAction::GeneratePrimaries
(G4Event* anEvent) = 0;
```



The GeneratePrimaries() method must be overridden in your implementation

# G4VUserPrimaryGeneratorAction::Purpose

- ▶ This class is **not** the generator of primaries, it is used to configure the generator
- ▶ GEANT4 delivers two generators that can be used in order to create the vertex of primaries: **G4ParticleGun** and **G4GeneralParticleSource**
- ▶ Both of them inherits from **G4VPrimaryGenerator**, and override the following method:

```
virtual void  
G4VPrimaryGenerator::GeneratePrimaryVertex(G4Event* evt) = 0;
```

# G4VUserPrimaryGeneratorAction::Usage

- ▶ The PrimaryGeneratorAction class should contain a **G4VPrimaryGenerator**

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- ▶ The PrimaryGeneratorAction class should contain a **G4VPrimaryGenerator**
- ▶ The method **G4VPrimaryGenerator::GeneratePrimaryVertex()** should be called inside of **GeneratePrimaries()**
- ▶ **G4ParticleGun** can be used to configure the beam at compile time



# G4VUserPrimaryGeneratorAction::Usage

- ▶ The PrimaryGeneratorAction class should contain a **G4VPrimaryGenerator**
- ▶ The method **G4VPrimaryGenerator::GeneratePrimaryVertex()** should be called inside of **GeneratePrimaries()**
- ▶ **G4ParticleGun** can be used to configure the beam at compile time

# G4VUserPrimaryGeneratorAction::Usage

- ▶ The PrimaryGeneratorAction class should contain a **G4VPrimaryGenerator**
- ▶ The method **G4VPrimaryGenerator::GeneratePrimaryVertex()** should be called inside of **GeneratePrimaries()**
- ▶ **G4ParticleGun** can be used to configure the beam at compile time
- ▶ **G4GeneralParticleSource** should be use to configure the beam at run time, through a configuration file

# Example::G4ParticleGun

```
PrimaryGeneratorAction::PrimaryGeneratorAction() :
    fParticleGun{ new G4ParticleGun(1) }
{
    G4ParticleTable* particleTable =
        G4ParticleTable::GetParticleTable();
    G4ParticleDefinition* particle =
        particleTable->FindParticle("proton");
    fParticleGun->SetParticleDefinition( particle );

    fParticleGun ->
        SetParticleMomentumDirection( G4ThreeVector(0.,0.,1.) );
    fParticleGun->SetParticleEnergy( 100.*MeV );
}
```

# Example::G4ParticuleGun

```
void PrimaryGeneratorAction::GeneratePrimaries (G4Event* anEvent)
{
    G4double x0 = 0, y0 = 0, z0 = -20 * CLHEP::cm;

    fParticleGun->SetParticlePosition (G4ThreeVector (x0, y0, z0));

    fParticleGun->GeneratePrimaryVertex (anEvent);
}
```

# Example::G4GeneralParticleSource

```
PrimaryGeneratorAction::PrimaryGeneratorAction () :  
    fGeneralParticleSource{ new G4GeneralParticleSource }  
{ }
```

```
void PrimaryGeneratorAction::GeneratePrimaries (G4Event* anEvent)  
{  
    fGeneralParticleSource->GeneratePrimaryVertex (anEvent) ;  
}
```

In the corresponding .mac configuration file:

```
/gps/particle proton  
/gps/ene/mono 100.0 MeV  
/gps/pos/centre 0 0 -20 cm  
/gps/direction 0 0 1
```

# Physics



---

# Point of entry: main()

```
runManager->SetUserInitialization(new PhysicsList);
```

# Point of entry: main()


```
runManager->SetUserInitialization(new PhysicsList);
```


```
void G4RunManager::SetUserInitialization  
                                (G4VUserPhysicsList* userInit)  
{  
    physicsList = userInit;  PhysicsList is registered  
    ...  
    physicsList->ConstructParticle(); //in kernel  
    ...  
}  The ConstructParticle method must be overridden
```



# Point of entry: main()

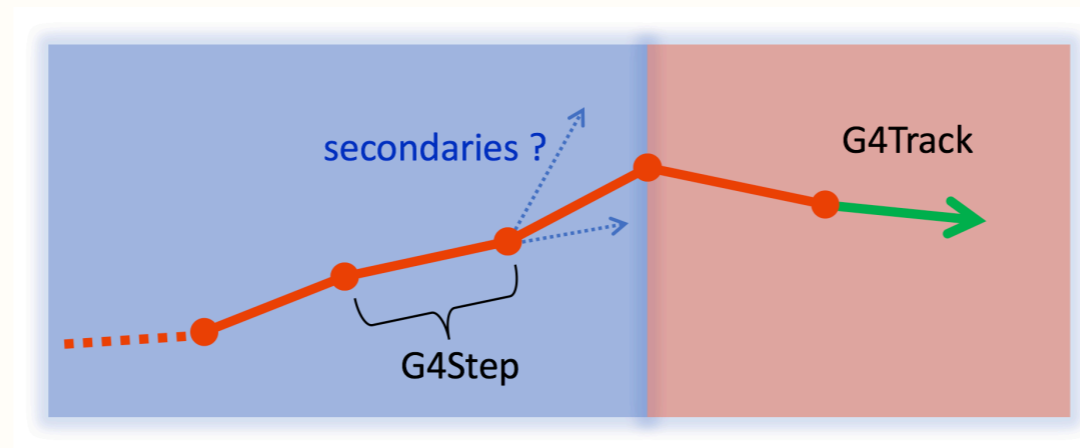
```
runManager->SetUserInitialization(new PhysicsList);
```

```
void G4RunManager::InitializePhysics()  
{  
    ...  
    if (physicsList)  Mandatory class  
    {  
        ...  
        physicsList->ConstructProcess();  
        ...  
    }  
    ...  
}
```

 **Must be overridden**

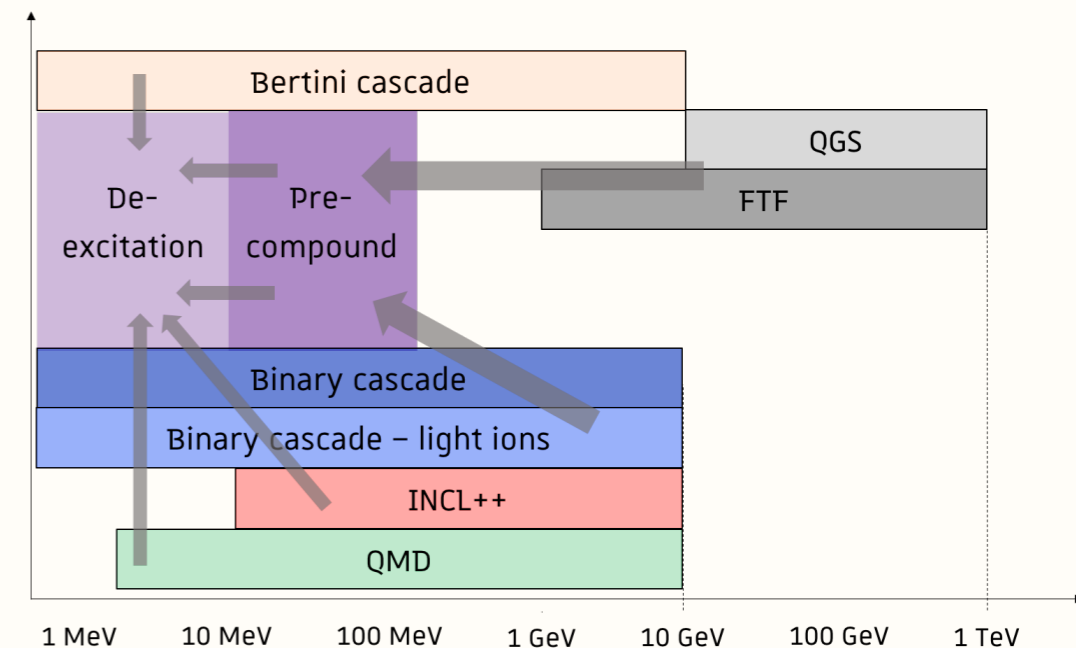
# PhysicsList::Purpose

- ▶ Implementation of real-world physics numerically
- ▶ Discretisation of continuous processes implies the use of “steps”, forming a “track” when put together
- ▶ The physics list is responsible for the registration of the particles, and of the processes they can undergo inside of the simulation



# PhysicsList::MainUsage

- ▶ Several ready-to-use physics lists are provided by the GEANT4 developers
- ▶ They are subdivided into modules handling some kind of physics: i.e., hadronic physics, electromagnetic physics, decays ...
- ▶ Different models can be used on a same energy range, you have to choose one, and eventually compare



# PhysicsList::MainUsage

- ▶ Non-exhaustive list of ready-to-use physics list:
  - QBBC
  - FTF\_BERT\_HP
  - FTFP\_INCLXX\_HP
  - QGSP\_BERT
  - QGSP\_BIC
  - QGSP\_INCLXX
  - ...

# G4VMModularPhysicsList

- ▶ Base class for the ready-to-use physics lists
- ▶ Register physics modules in its constructor:

```
void G4VMModularPhysicsList::RegisterPhysics  
    (G4VPhysicsConstructor* fPhysics)
```

 Base class for a physics module

# G4VMModularPhysicsList

- ▶ Base class for the ready-to-use physics lists
- ▶ Register physics modules in its constructor:

```
void G4VMModularPhysicsList::RegisterPhysics  
    (G4VPhysicsConstructor* fPhysics)
```

→ Base class for a physics module

```
PhysicsList::PhysicsList()
```

```
{  
    RegisterPhysics(new G4DecayPhysics);  
    RegisterPhysics(new G4EmStandardPhysics);  
    RegisterPhysics(new G4RadioactiveDecayPhysics);  
}
```

→ Necessary modules to describe radioactive decay

# PhysicsListCustomization::Example

```
class PhysicsList final : public G4VModularPhysicsList
{
public:
    PhysicsList();
    void ConstructProcess() override;
};
```

```
PhysicsList::PhysicsList()
```

```
{
    RegisterPhysics ( new G4EmStandardPhysics );
    RegisterPhysics ( new G4EmExtraPhysics );
    RegisterPhysics ( new G4DecayPhysics );
    RegisterPhysics ( new G4HadronElasticPhysics );
    RegisterPhysics ( new G4HadronPhysicsQGSP_BIC );
    RegisterPhysics ( new G4StoppingPhysics );
    RegisterPhysics ( new G4IonPhysics );
    RegisterPhysics ( new G4NeutronTrackingCut );
}
```

Registration of all the modules



# PhysicsListCustomization::Example

```
class PhysicsList final : public G4VModularPhysicsList
{
public:
    PhysicsList();
    void ConstructProcess() override;
};
```

```
void PhysicsList::ConstructProcess()
{
    G4VModularPhysicsList::ConstructProcess();

    auto* proton = G4Proton::Definition();
    auto* manager = proton->GetProcessManager();
    auto* msc = manager->GetProcess("msc");
    manager->RemoveProcess(msc);
}
```

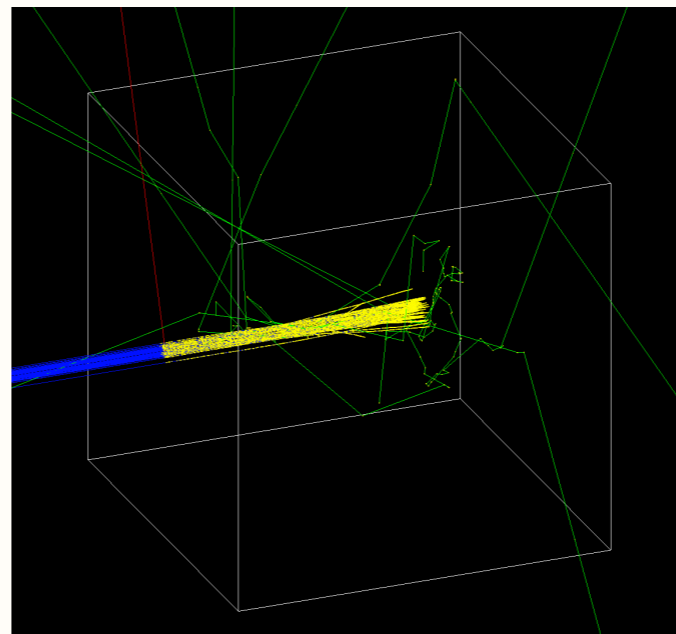
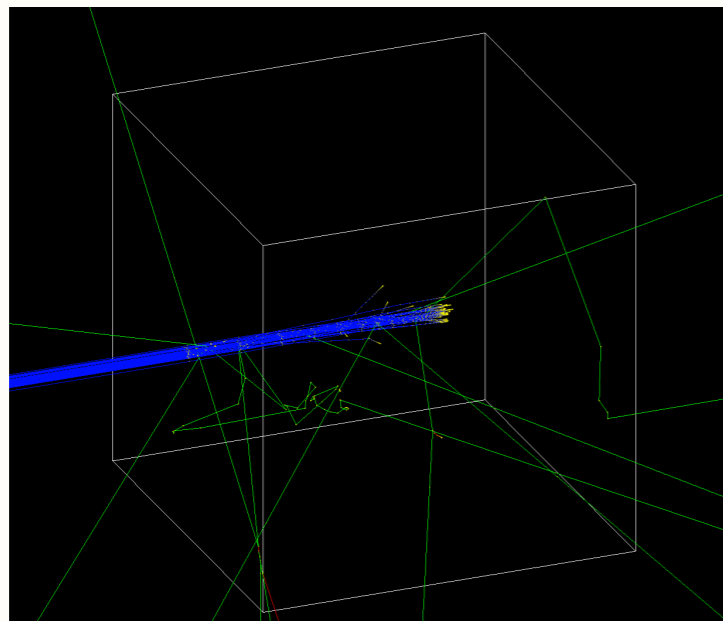
Construction of the processes

Removing the multiple coulomb scattering for the protons



# Production cuts

- ▶ In order to reduce the computational load, production cuts are used
- ▶ Some secondaries ( $\gamma$ ,  $e^-$ ,  $e^+$ ) are only produced and transported if their energy is sufficient to propagate farther than a pre-defined distance : it is the cut value (1 mm by default)



```
/run/setCuts 10 um
```

# Exercise

- ▶ Goal : preparation of several macros reproducing the gamma lines of interest (isotropic and cylindric source)
  
- ▶ Three difficulty levels:
  - ◎ (A) Fill-in the blanks
  - ◎ (B) Guided construction
  - ◎ (C) Empty class
  
- ▶ Retrieve the chosen files in:  
`/scratch/asecher/Geant4/beam&physics_exercise`
  
- ▶ Do not forget to uncomment the corresponding lines in your main

# Data retrieval

---

# Point of entry: main()


```
auto* runAction = new RunAction;
runManager->SetUserAction( runAction ) ;


auto* eventAction = new EventAction{ runAction };
runManager->SetUserAction( eventAction ) ;

runManager->SetUserAction( new SteppingAction{ eventAction } );
```

```
void G4RunManager::SetUserAction(G4UserRunAction* userAction)
{
    userRunAction = userAction;
}

```

 Base class

 Registering


# Point of entry: main()


```
auto* runAction = new RunAction;
runManager->SetUserAction( runAction ) ;

auto* eventAction = new EventAction{ runAction };
runManager->SetUserAction( eventAction ) ;

runManager->SetUserAction( new SteppingAction{ eventAction } );
```

```
void G4RunManager::SetUserAction(G4UserEventAction* userAction)
{
    eventManager->SetUserAction(userAction);
    userEventAction = userAction;
}
```

 Base class

 Registering


# Point of entry: main()


```
auto* runAction = new RunAction;
runManager->SetUserAction( runAction ) ;

auto* eventAction = new EventAction{ runAction };
runManager->SetUserAction( eventAction ) ;

runManager->SetUserAction( new SteppingAction{ eventAction } );
```

```
void G4RunManager::SetUserAction(G4UserSteppingAction* userAction)
{
    eventManager->SetUserAction(userAction);
    userSteppingAction = userAction;
}
```


 Base class

 Registering


# Outline of a run

```
void G4RunManager::BeamOn( G4int n_event,
                           const char* macroFile,
                           G4int n_select
                           )
{
    ...
    RunInitialization();
    DoEventLoop(n_event, macroFile, n_select);
    RunTermination();
    ...
}
```

```
void G4RunManager::RunInitialization()
{
    ...
    if (userRunAction) userRunAction->BeginOfRunAction(currentRun);
    ...
}
```

 Should be overridden

# Outline of a run


```
void G4RunManager::BeamOn( G4int n_event,  
                           const char* macroFile,  
                           G4int n_select  
                           )  
{  
    ...  
    RunInitialization();  
    DoEventLoop(n_event, macroFile, n_select);  
    RunTermination();  
    ...  
}  
  
void G4RunManager::DoEventLoop(...)  
{  
    ...  
     currentEvent = GenerateEvent(i_event);  
    eventManager->ProcessOneEvent(currentEvent);  
    ...  
}
```



# Outline of a run

```
void G4RunManager::BeamOn( G4int n_event,
                           const char* macroFile,
                           G4int n_select
                           )
{
    ...
    RunInitialization();
    DoEventLoop(n_event, macroFile, n_select);
    RunTermination();
    ...
}


void G4RunManager::RunTermination()
{
    ....
    if(userRunAction) userRunAction->EndOfRunAction(currentRun);
    ...
}
```

 Should be overridden

# Outline of a run

```
void G4RunManager::BeamOn( G4int n_event,
                           const char* macroFile,
                           G4int n_select
                           )
{
    ...
    RunInitialization();
    DoEventLoop(n_event, macroFile, n_select);
    RunTermination();
    ...
}

void G4RunManager::RunTermination()
{
    ....
    if(userRunAction) userRunAction->EndOfRunAction(currentRun);
    ...
}
```

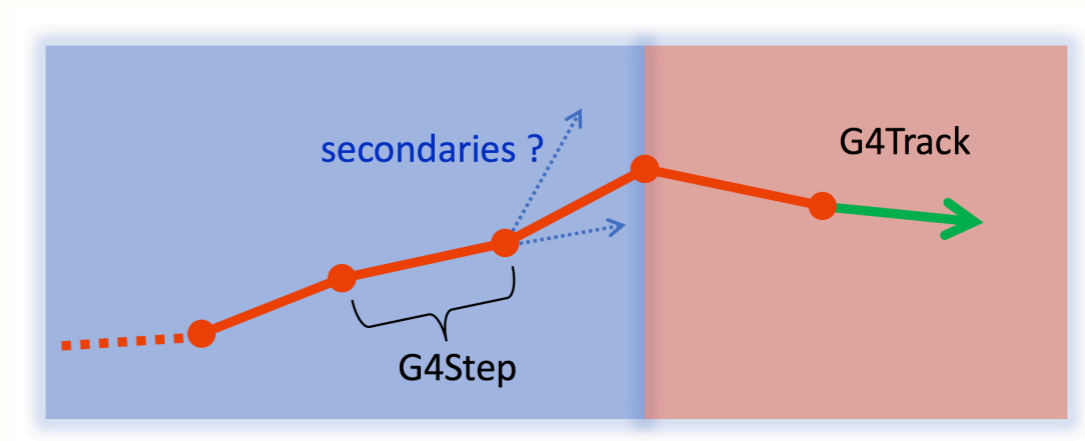
 Should be overridden

# Outline of a run

```
void G4EventManager::ProcessOneEvent (G4Event* anEvent)
{
    ...
    trackContainer->PrepareNewEvent ();
    ...
    trackManager->ProcessOneTrack ( track );
    ...
}
```


```
void G4TrackingManager::ProcessOneTrack (G4Track* apValueG4Track)
{
    ...
    fpSteppingManager->Stepping ();
    ...
}
```

Additional tracks will eventually be added to the track container



# Outline of a run

```
G4StepStatus G4SteppingManager::Stepping()
{
    ...
    if ( fUserSteppingAction != 0 ) {
        fUserSteppingAction->UserSteppingAction(fStep);
    }
    ...
}
```

 Should be overridden

# RunAction::example

```
RunAction::RunAction () :
    fEvents{-1},
    fEdep{-1.},
    fDepth{0.},
    fPartName{"unknown"},
    fTrackID{0},
    fParentID{-1},
    fTree{"tree", "tree"}
{
    fTree.Branch("Edep", &fEdep, "Edep /D");
    fTree.Branch("Depth", &fDepth, "Depth /D");
    fTree.Branch("ptclName", &fPartName);
    fTree.Branch("trackID", &fTrackID, "trackID /I");
    fTree.Branch("parentID", &fParentID, "parentID /I");
}
```

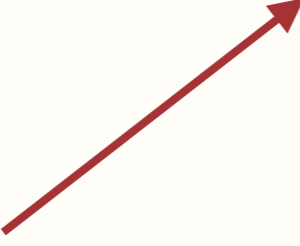
# RunAction::example

```

RunAction::RunAction () :
    fEvents{-1},
    fEdep{-1.},
    fDepth{0.},
    fPartName{"unknown"},
    fTrackID{0},
    fParentID{-1},
    fTree{"tree", "tree"}
{
    fTree.Branch("Edep", &fEdep, "Edep /D");
    fTree.Branch("Depth", &fDepth, "Depth /D");
    fTree.Branch("ptclName", &fPartName);
    fTree.Branch("trackID", &fTrackID, "trackID /I");
    fTree.Branch("parentID", &fParentID, "parentID /I");
}

```

TTree ( const char \*name,  
 const char \*title, ... )



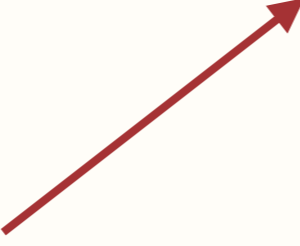
# RunAction::example


```

RunAction::RunAction () :
    fEvents{-1},
    fEdep{-1.},
    fDepth{0.},
    fPartName{"unknown"},
    fTrackID{0},
    fParentID{-1},
    fTree{"tree", "tree"}
{
    fTree.Branch("Edep", &fEdep, "Edep /D");
    fTree.Branch("Depth", &fDepth, "Depth /D");
    fTree.Branch("ptclName", &fPartName);
    fTree.Branch("trackID", &fTrackID, "trackID /I");
    fTree.Branch("parentID", &fParentID, "parentID /I");
}

```

**TTree** ( const char \*name,  
const char \*title, ... )





```

TBranch* TTree::Branch ( const char * name,
void * address,
const char * leaflist, ... )

```

# RunAction::example

```
void RunAction::BeginOfRunAction (const G4Run* aRun)
{
    fEvents = aRun->GetNumberOfEventToBeProcessed();
}
```

```
void RunAction::EndOfRunAction ( const G4Run* )
{
    TFile outputFile{"Output.root", "recreate"};
    fTree.Write() ;
    outputFile.Close() ;
}
```

 Creation and filling of the root file



# SteppingAction::Example

```
void SteppingAction::UserSteppingAction(const G4Step* step)
{
    auto* track_h = step->GetTrack() ;
    if( track_h->GetVolume()->GetName() == "Phantom" ) {

        auto* runAction_h = fEventAction->GetRunAction() ;
        runAction_h->SetEdep( step->GetTotalEnergyDeposit() *
                             CLHEP::MeV ) ;

        ...
        runAction_h->SetTrackID( track_h->GetTrackID() ) ;
        ...

        runAction_h->GetTree().Fill() ;
    }
}
```

The tree is filled here, at each step inside of the "Phantom" volume

# Exercise

- ▶ Goal : return the number of primary photons entering the detector, and deduce the corresponding acceptance
- ▶ Three difficulty levels:
  - ◎ (A) Fill-in the blanks
  - ◎ (B) Guided construction
  - ◎ (C) Empty class
  - ◎ (C+) Add a way to retrieve the energy spectrum
- ▶ Retrieve the chosen files in:  
`/scratch/asecher/Geant4/data_exercise`
- ▶ Do not forget to uncomment the corresponding lines in your main